

FD422 Series Servo Driver

FEATURES

- **Input Voltage Range From 176-253VAC**
- **Rated Current is (RMS) 4A**
- **200-750 Watt Power Range**
- **Position, Speed, and Torque Control**
- **RS232 and RS485 or CAN BUS Communication Ports**
- **Natural Air Cooling**
- **MODBUS and CANopen Standard**
- **Requires 2500PPR Encoder Input**
- **Communication Software**
 - **Configure Parameters**
 - **I/O Signal Monitoring**
 - **Speed and Poaition Curves**
 - **Gain Adjustments**
- **Programmable Inputs and Outputs**
 - **7 Inputs**
 - **4 Outputs**
- **CE Certified**



DESCRIPTION

The FD422 Series Servo Drive is a great fit for applications requiring position, speed and/or torque control methods. The uniqueness of this servo drive is the flexibility of using a single servo drive that can accomodate motors with power ratings ranging from 200-750W. Also it is designed to switch dynamically among different control methods for more flexible operation. The FD422 Series Servo Drive operates with single-phase 176-253VDC input. The FD422-LA-000 comes standard with RS232 and RS485 communication ports, and can be operated using MODBUS Protocol. FD422-AA-000 and FD422-CA-000 drives have RS232 and CANbus communication interfaces, using CANopen Protocol. All FD422 Series servo drives are operational using our free, easy-to-use software.

SPECIFICATIONS

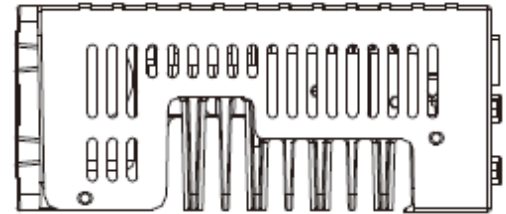
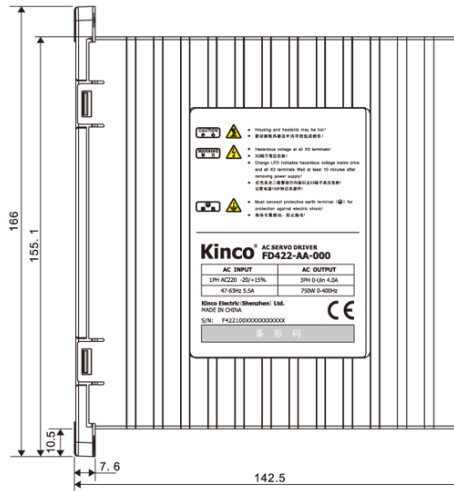
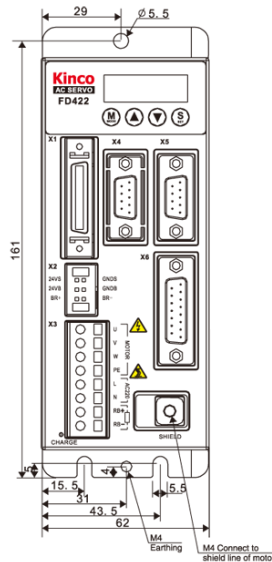
Category	Servo Driver	Servo Motor	Description	Power/Brake Cable	Encoder Cable	Rated Speed/ Rated Torque/ Rated Current
Small Inertia 220V	FD422-LA-000 FD422-CA-000 FD422-AA-000	SMH60S-0020-30AAK-3LKH	Cable Connector	MOT-005-05-KL	ENCCA-05-KH	3000rpm/ 0.64Nm/ 1.6A
		SMH60S-0020-30ABK-3LKH	Cable Connector and Brake	MOT-005-05-KL/ BRA-05-KL		
		SMH60S-0020-30AAK-3LKN	HFO Standard Connector	MOT-005-05-KC0	ENCCA-05-KC0	ENCCA-05-KM1
		SMH60S-0020-30AAK-3LKM	Intercontec Connector	MOT-005-05-KM1		
		SMH60S-0020-30ABK-3LKM	Intercontec Connector w/Brake	MOT-005-05-KM1-B		
		SMH60S-0040-30AAK-3LKH	Cable Connector	MOT-005-05-KL	ENCCA-05-KH	3000rpm/ 1.27Nm/ 3.1A
		SMH60S-0040-30ABK-3LKH	Cable Connector and Brake	MOT-005-05-KL/ BRA-05-KL		
		SMH60S-0040-30AAK-3LKN	HFO Standard Connector	MOT-005-05-KC0	ENCCA-05-KC0	ENCCA-05-KM1
		SMH60S-0040-30AAK-3LKM	Intercontec Connector	MOT-005-05-KM1		
		SMH60S-0040-30ABK-3LKM	Intercontec Connector w/Brake	MOT-005-05-KM1-B		

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Category	Servo Driver	Servo Motor	Description	Power/Brake Cable	Encoder Cable	Rated Speed/ Rated Torque/ Rated Current
Small Inertia 220V	FD422-LA-000 FD422-CA-000 FD422-AA-000	SMH80S-0075-30AAK-3LKH	Cable Connector	MOT-005-05-KL	ENCCA-05-KH	3000rpm/ 2.39Nm/ 3.9A
		SMH80S-0075-30ABK-3LKH	Cable Connector and Brake	MOT-005-05-KL/ BRA-LL-KL		
		SMH80S-0075-30AAK-3LKN	HFO Standard Connector	MOT-005-05-KC0	ENCCA-05-KC0	
		SMH80S-0075-30AAK-3LKM	Intercontec Connector	MOT-005-05-KM1	ENCCA-05-KM1	
		SMH80S-0075-30ABK-3LKM	Intercontec Connector w/ Brake	MOT-005-05-KM1-B		
		SME60S-0020-30AAK-3LKH	Cable Connector	MOT-005-05-KL	ENCCF-05-FH	3000rpm/ 0.64Nm/ 1.6A
		SME60S-0020-30ABK-3LKH	Cable Connector and Brake	MOT-005-05-KL/ BRA-LL-KL		
		SME60S-0040-30AAK-3LKH	Cable Connector	MOT-005-05-KL	ENCCF-05-FH	3000rpm/ 1.27Nm/ 3.1A
		SME60S-0040-30ABK-3LKH	Cable Connector and Brake	MOT-005-05-KL/ BRA-LL-KL		

SPECIFICATIONS



Note: All Dimensions in (mm)

Model Parameter		FD422- A Series
Operation Environment	Operating Temperature	0 ~ 40°C
	Storage Temperature	-10° C~70°C
	Humidity (Non-Condensing)	Below 90%RH
	Protection Class	IP20
	Installation Environment	Installed in a Dust-Free, Dry and Lockable Environment (Such as in a Electrical Cabinet)
	Installation Mode	Vertical Installation
	Altitude	No Power Limitation Below 1000m
	Atmospheric Pressure	86kpa-106kpa

Model Parameter		FD422- <input type="checkbox"/> A-000 Series
Power	Main Supply Voltage	Single-Phase AC 220V -20/+15% 47~63Hz
	Control Circuit Voltage	18VDC~30VDC 1A
Current	Rated Current (RMS)	4A
	Peak Current (PEAK)	15A
Feedback Signal		2500PPR (Incremental Encoder with 5V Supply)
Brake Chopper		Use an External Braking Resistor According to Application, Mainly in Occasion of Quick Stop.
Brake Chopper Threshold		DC380V \pm 5V
Over-Voltage Alarming Threshold		DC400V \pm 5V
Under-Voltage Alarming Threshold		DC200V \pm 5V
Cooling Method		Natural Air Cooling
Weight		1.2 Kg
Digital Input	Input Specification	7 Digital Inputs, with COM1 Terminal for PNP (High Level Valid 12.5-30V) or NPN (Low Level Valid) connection.
	Input Function	Define Freely According to Requirement, Supporting Following Functions: Driver Enable, Driver Fault Reset, Driver Mode Control, Proportional Control, Positive Limit, Negative Limit, Homing Signal, Reverse Command, Internal Speed Section Control, Internal Positive Section Control, Quick Stop, Start Homing, Active Command, Switch Electronic Gear Ratio, Switch Gain.
Digital Output	Output Specification	5 Digital outputs, OUT1~OUT4 Current is 100mA, BR+/BR- (Brake Control Output) Current is 500mA, Can Drive Brake Device Directly.
	Output Function	Define Freely According to Requirement, Supporting Following Functions: Driver Ready, Driver Fault, Position Reached, Motor at Zero Speed, Motor Brake, Motor Speed Reached, Z Signal, Maximum Speed Obtained in Torque Mode, Motor Brake, Position Limiting, Reference Found, Multi-Position Reached
	Analog Input	2 Analog input, can be used to control speed and Torque, the input range is -10V~10V
	Encoder Signal Output	Output the Encoder Signal of Motor, Used in Multiple Axis Synchronous Control, Supports 2MHz at Most
	RS232	The Max. Baudrate is 115.2KHz, Use JD-PC Software to communicate with PC, or Via Free Protocol to communicate with Controller.
	Protection Functions	Over-Voltage Protection, Under-Voltage Protection, Motor Over-Heat Protection (I^2T), Short-Circuit Protection, Drive Over-Heat Protection, Etc.
RS485		The max. baudrate is 115.2 KHz, use Modbus RTU protocol to communicate with controller.
CAN BUS		The max baudrate is 1 MHz, Communicates with Controller via CANopen Protocol

Note: =L: Communication Port RS232, RS485
=A/C: Communication Port RS232, CANopen

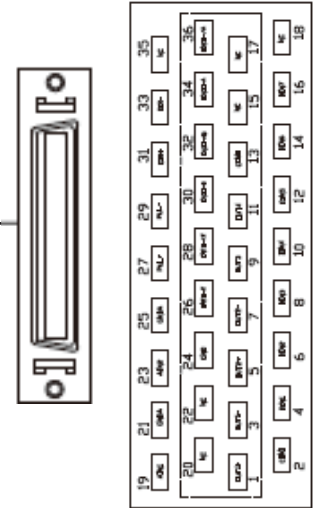
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Digital Input/Output Interface

PIN No.	Signal	PIN No.	Signal	PIN No.	Signal	PIN No.	Signal
2	COM1	1	OUT1+	20	NC	19	AIN1
4	DIN1	3	OUT1-	22	NC	21	GNDA
6	DIN2	5	OUT2+	24	GND	23	AIN2
8	DIN3	7	OUT2-	26	ENCO-Z	25	GNDA
10	DIN4	9	OUT3	28	ENCO-Z	27	PUL+
12	DIN5	11	OUT4	30	ENCO-B	29	PUL-
14	DIN6	13	COM0	32	ENCO-B	31	DIR+
16	DIN7	15	NC	34	ENCO-A	33	DIR-
18	NC	17	NC	36	ENCO-A	35	NC

X1



RS485

PIN Number	Signal
1	NC
2	RX+
3	TX+
4	NC
5	GND
6	+5V
7	RX-
8	TX-
9	NC

CAN

PIN Number	Signal
1	NC
2	CAN_L
3	GND
4	NC
5	NC
6	NC
7	CAN_H
8	NC
9	NC

X4

Male: CANbus
Communication Port
Female: RS485
Communication Port



9 pin DB

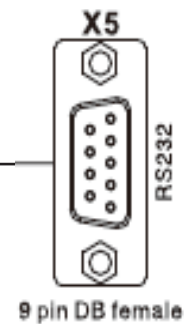
RS232

ENCODER IN

PIN No.	Signal
1	+5V
2	A
3	B
4	Z
5	U
6	V
7	W
8	PTC_IN
9	GND
10	/A
11	/B
12	/Z
13	/U
14	/V
15	/W

PIN Number	Signal
1	NC
2	TX
3	RX
4	NC
5	GND
6	NC
7	NC
8	NC
9	NC

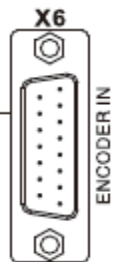
X5



9 pin DB female

Motor Encoder Input
Port

X6



15 pin DB female

INTERFACE DESCRIPTION